



Introduction of LSSVR for the Prediction of the Yellowness Index

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Abstract: Data-driven models including principal component regression (PCR), partial least square regression (PLSR), and least square support vector regression (LSSVR) have been widely applied as predictive models in various applications. However, studies employing regression models to estimate the yellowness index (YI) are scarce in the literature. This study, therefore, focuses on developing non-destructive YI measurements using regression models. The collected RGB calculated XYZ and obtained CIE LAB values were set as the input variables. Meanwhile, the YI value was denoted as the output variable. Results indicated that the LSSVR model outperforms PCR and PLSR models in predicting YI in which the root means square errors of LSSVR for the training and testing datasets were found to be 261,406% to 294,218% and 725% to 772% lower than PLSR and PCR, respectively. LSSVR is also attributed to higher coefficients of determination (R^2) that are superior to PLSR and PCR, whose R^2 values are very close to 1. Nonetheless, the computational times of training and testing datasets for LSSVR are much longer than those of PLSR and PCR. Consequently, a highly accurate LSSVR model-based YI sensor shows promising applications particularly if the computational load can be further minimized.

Keywords: Least square support vector regression, Yellow color, Model, Algorithm, Yellowness Index

1. INTRODUCTION

Current modern manufacturing processes have a strong requirement for effective and rapid computing modeling, such as soft sensors to monitor, control, optimize, and automate their chemical processes to enhance Industry 4.0. For instance, the purities of fatty acid and glycerol via hydrolysis of palm oil are required to be monitored and optimized to have a better quality [1], [2]. Hence, a data strategy that systematically connects industry 4.0 technologies and data analysis with sector-specific competencies, especially since it is associated with the newest advances in soft sensors. Moreover, a soft sensor is one of the advances in modern statistics and computing technology that can bring new chances to form novel or improved evaluation techniques [3]. A soft sensor utilizes regression analysis that involves a set of machine learning techniques allowing the prediction of a continuous output variable based on the value of one or multiple predictor variables or input variables [4], [5]. To be more specific, the soft sensor model is used for the forecast of future targeted data based on the correlation between individual variables to have an optimized and productive operating process when it is incorporated into a processing system [6]. To date, soft sensor models have been widely studied to predict accuracy for the targeted and desired variable for superior chemical process monitoring and controlling a process to produce a

good quality product [7].

The least-square support vector regression (LSSVR) was introduced by Suykens, et al. [8] is one of the regression models that is modified from support vector regression (SVR). The difference between LSSVR from SVR is that it solves a set of linear systems to obtain the solution instead of solving a quadratic program problem. Hence, LSSVR is simpler and has a lower computational load as compared to SVR. The effectiveness of LSSVR has been widely studied by Yu, et al. [9] in measuring the ecological parameters of rice wine, Sivaramakrishnan, et al. [10] in estimating the concentrations of a product in an acid-catalyzed propylene oligomerization, and Yeo and Lau [11] in forecasting the whiteness index of fabric. Meanwhile, these studies also included the predictive performance comparison of LSSVR with partial least square regression (PLSR) which is another frequently used regression model. However, they did not consider the prediction of the yellowness index (YI) using LSSVR and the comparison of LSSVR and PLSR on YI prediction has not been carried out.

On the other hand, both PLSR and principal component regression (PCR) become popular models in estimating the quality, and process monitoring in a process control system due to their simplicities [12], [13]. Moreover, these two

models have been studied by many researchers such as Singh and Sarkar [14], Ergon, et al. [15], Ergon [16], and Engelen, et al. [17]. PCR is an extension regression analysis method of PCR that consists of principal component analysis (PCA). This PCA model is a famous unsupervised dimensionality reduction mathematical technique that separates data where perceptions can be represented by the collective relation of the input variable that connects to the current PLSR application [18]. On the other hand, PCR searches a small scale space grabbing the optimum estimation of the dissimilarity in independent variables, X . Meanwhile, the PLSR technique is the same as PCR but PLSR differs by including the measurement of the dependent and independent variables to predict the targeted output variable [12].

Nevertheless, PLSR discovers hybrid features from PCA and multiple linear regression [19]. PLSR-based models are usually derived using Nonlinear Iterative Partial Least Squares (NIPALS) and singular value decomposition (SVD). NIPALS performs superior to SVD since it is faster, can handle missing data, and determines the components sequentially [20], [21]. Thus, the majority of PLSR-based algorithms are developed based on the NIPALS-based algorithm [22]. Since the invention of NIPALS, PLSR has been recognized as a popular model for modeling and analyzing huge multivariable collinear sets of data [23] since it is a dimension-reduction method. Additionally, PLSR has been applied for data analysis in various fields such as the dynamic monitoring oxidation process of nut oils done by Wang, et al. [24], hyperspectral prediction of soil organic matter content studied by Shen, et al. [25], and forecasting chemical properties of fish muscle conducted by Cheng and Sun [26]. However, a limited color-related study is using the abovementioned PLSR, PCR, and LSSVR. The color index like YI is a reference for all colorants such as dye, and pigment [27] [27] and it is a simple numerical expression that determines the color of an object. YI is a value that denotes the departure level of a sample's color from a desired white and becomes yellow [28], [29].

Due to the importance of color in a range of products and technologies, color engineering has been established to synthesize the disciplines of color science and computer engineering [30]. Moreover, color engineering is essential in the development of color imaging products in some big companies like Google, Apple, Samsung, Amazon, etc. Besides, color is a critical quality attribute in industries like paints, chemicals, and agriculture industries ensuring consistent color in products is crucial for meeting customer expectations and maintaining product quality. This is because the color is an organoleptic characteristic that affects consumers' preference to adopt an item. Furthermore, color has a strong connection to product quality. Hence, color has been studied by many researchers [31], [32], [33], [34]. Despite that, the majority of studies used expensive color measurement instruments including colorimeter, and spectrophotometer. Moreover, they can only determine the color

space data for color index calculation, and these instruments cannot measure the color index directly. On top of that, YI was studied by Blanco, et al. [35] and Digesù, et al. [36] to investigate the wheat quality. However, research studies focusing on YI, especially using soft sensor models, remain limited. In other words, YI is computed from color scale parameters that assess perceptual yellowness. However, the color data to calculate YI values is usually measured by expensive hardware instruments. Furthermore, a direct and rapid YI estimation utilizing this hardware equipment is impossible. And, soft sensors models could be a potential solution to this problem statement.

To address the abovementioned research gaps, the current study focuses on obtaining a low-cost, rapid, and straightforward YI measurement technique. This comparative study was carried out to examine the performances of the PLSR, LSSVR, and PCR methods to forecast the YI using the color space data. Then, an RGB-listed standard color chart was employed to collect the dataset for the LSSVR, PLSR, and PCR models. Later, the RGB can be converted into CIE LAB and CIE XYZ [37]. The YI values can be obtained from the CIE XYZ. The performances of LSSVR, PLSR, and PCR models were measured and distinguished. In other words, the outcomes of the performances for LSSVR, PLSR, and PCR including coefficients of determination (\mathbb{R}^2), root mean square error (RMSE), mean absolute errors (MAE), and computation times (t) were adopted and compared among them.

2. MATERIALS AND METHODS

This section is divided into seven sub-sections to explain the research materials and methods that were used in this study. Firstly, this section describes the LSSVR method. Next, it is followed by data splitting, parameter setting, different color space conversions, as well as YI computation. Then, data generation, predictive performance analysis, and computer configuration are described.

A. Least square support vector regression model

As compared to the SVR that has quadratic programming, LSSVR provides a more effective solution with lower computational complexity and time since LSSVR solves a set of linear equations [38]. The LSSVR with radial basis function (RBF) kernel is utilized in this study. Kernel functions have been utilized for pattern recognition, regression, approximation, and operator inversion [39]. The effectiveness of LSSVR has been recently proven by Pervez, et al. [40], Ngu and Yeo [41], and Yeo and Lau [11]. This LSSVR was introduced by Xu, et al. [42] and it adopts the multi-output case that was conducted by An, et al. [43]. And this multi-output setting in this LSSVR makes it provides a better training algorithm. The LSSVR model is briefly explained in this section and it was taken from Xu, et al. [42] and Yeo and Lau [11]. Let $Y = [y_{i,j}] \in \mathbb{R}^{l \times m}$, $y_{i,j}$ is the (i,j)-th of output with an $l \times m$ matrix. For a provided total number of datasets, N_T , i.e., $\{(x_i, y^i)\}_{i=1}^l$ in which $x_i \in \mathbb{R}^d$ is the input vector and $y^i \in \mathbb{R}^m$ is the

output vector. Moreover, the objective of the LSSVR is to estimate an output vector $y \in \mathfrak{R}^m$ from a provided input vector $x \in \mathfrak{R}^d$ in which this regression issue is able to form by learning a mapping from \mathfrak{R}^d to \mathfrak{R}^m . Then, this LSSVR provides solutions for the regression issue by finding the weighted value vector, $W = (w_1, w_2, \dots, w_m) \in \mathfrak{R}^{n_h \times m}$ and a threshold value, $b = (b_1, b_2, \dots, b_m)^T \in \mathfrak{R}^m$ to meet the following targeted objective function with its constraints in 1 and 2:

$$\min_{W \in \mathfrak{R}^{n_h \times m}, b \in \mathfrak{R}^m} \frac{1}{2} \gamma^T \gamma \quad (1)$$

$$s.t. Y = Z^T W + repmat(b^T, l, 1) + \Xi \quad (2)$$

where γ is a non-negative real regularised parameter, $\xi = (\xi_1, \xi_2, \dots, \xi_l)^T \in \mathfrak{R}^l$ is a vector having slack variables, $Z = (\phi(x_1), \phi(x_2), \dots, \phi(x_l)) \in \mathfrak{R}^{n_h \times l}$, $\phi : \mathfrak{R}^d \rightarrow \mathfrak{R}^{n_h}$ is a data mapping to an infinite dimensional Hilbert feature space through the nonlinear mapping function ϕ with n_h dimensions, and $\Xi = (\xi_1, \xi_2, \dots, \xi_m) \in \mathfrak{R}_+^{l \times m}$ is an $l \times m$ order of matrix containing slack variables with \mathfrak{R}_+ . More details about this LSSVR model can be found in Xu, et al. [42] [42].

The RBF that is employed as a kernel function in the LSSVR is taken from Keerthi and Lin [44]. It is displayed in 3 and is integrated into the LSSVR.

$$k(x, z) = e^{(-p\|x-z\|^2)} \quad (3)$$

where p is the non-negative hyperparameter of the RBF kernel function. Furthermore, LSSVR has three tuning parameters involving γ , λ , and p that are tuned via the leave-one-out (LOO) technique to achieve the mean relative error, δ that is displayed in 4.

$$\delta = \frac{1}{l} \sum_{i=1}^l \frac{|Y_i - \hat{Y}_i|}{Y_i} \quad (4)$$

where Y_i and \hat{Y}_i are the real and the predicted outputs, respectively.

B. Splitting of data and parameters setting

In this study, there were 76 datasets consisting of the values of YI, XYZ, RGB, and LAB were gathered from the RGB-listed color charts. Later, the collected datasets were transferred into MATLAB software, and then 75% of the training and 25% of the testing data were utilized [45]. The training data was utilized to formulate LSSVR, PLSR, and PCR models. Later, these split datasets were run using these three regression models, and then model evaluations were carried out [46]. Then, the values of RMSE, MAE, R^2 , and computational times, t in seconds for all models were obtained. All regression model values adopted in the three are shown in Table I. The total number of the dataset, N_T was split into a number of the training dataset, N_1 , and a number of the testing dataset, N_2 . Moreover, LV which is the number of LV was set as 1. Meanwhile, γ , λ , and p in the LSSVR model were tuned using the LOO method. The estimation of the LOO method for these three feature

values is calculated from the training datasets and they are fixed for both training and testing datasets.

C. Color spaces transformations and yellowness index computation

RGB is the opposite of cyan, magenta, yellow, and key (black) (CMYK) which is another color space because it is an “additive” process. RGB utilizes white as an integration of all primary colors and black without the presence of light. On the contrary, CMYK employs white as the natural color of the print background and black as the integration of colored inks. RGB color space is recognized as the famous color space and RGB is integrated to form a color [47]. Nonidentical color needs not to have the same quantity of RGB, and the amount required for R, G, and B to build color is denoted as tristimulus values that are X, Y, and Z [48]. They are intermediate color spaces and the coordinating of RGB values that demonstrate any available color with the lightness information involved [49]. Barbero-Álvarez, et al. [49] reported that the XYZ values can be calculated from the RGB values using 5 to 7.

$$X = 0.4125R + 0.3576G + 0.1804B \quad (5)$$

$$Y = 0.2127R + 0.7152G + 0.0722B \quad (6)$$

$$Z = 0.0193R + 0.1192G + 0.9503B \quad (7)$$

Particularly, YI can be obtained from the American Society for Testing and Materials 313-00 which is described as 8 [34].

$$YI = \frac{(100(1.3013X - 1.1498Z))}{Y} \quad (8)$$

Moreover, XYZ values are used to estimate the CIE L * a * b * color values [50]. 9 and 10 explain these CIE L * a * b * color values that are normalized to the reference white [51].

$$L^* = 116 \sqrt[3]{\frac{Y}{Y_n}} - 16$$

$$a^* = 500 \left(\sqrt[3]{\frac{X}{X_n}} - \sqrt[3]{\frac{Y}{Y_n}} \right)$$

$$b^* = 200 \left(\sqrt[3]{\frac{Y}{Y_n}} - \sqrt[3]{\frac{Z}{Z_n}} \right)$$

(9)

where the $\frac{X}{X_n}$, $\frac{Y}{Y_n}$, and $\frac{Z}{Z_n}$ are larger than 0.008856.

$$L^* = 903.3 \left(\frac{Y}{Y_n} \right)$$

$$a^* = 500 \left\{ \left[7.87 \left(\frac{X}{X_n} \right) + \frac{16}{116} \right] - \left[7.87 \left(\frac{Y}{Y_n} \right) + \frac{16}{116} \right] \right\}$$

$$b^* = 200 \left\{ \left[7.87 \left(\frac{X}{X_n} \right) + \frac{16}{116} \right] - \left[7.87 \left(\frac{Z}{Z_n} \right) + \frac{16}{116} \right] \right\}$$

(10)

TABLE I. The parametric quantity and amounts employed for the least-square regression methods

Parametric quantity	N_T	N_1	N_2	LV	γ	λ	p
Amounts	76	57	19	1	15	10	3

where the $\frac{X}{X_n}$, $\frac{Y}{Y_n}$, and $\frac{Z}{Z_n}$ are equal to or lesser than 0.008856.

D. Data generation

An RGB-listed standard color chart was utilized to gather data for formulating and testing the used methods in this study. The RGB values on the color chart were used to calculate the YI values. These RGB values were initially input into Eqs. (12) to (14). Next, the obtained XYZ values were filled into eq. (15) to calculate the YI. Then, with these XYZ values, Eqs. (16) and (17) are used to get the CIE LAB values. In LSSVR, PLSR, and PCR models, the collected RGB, calculated XYZ and obtained CIE LAB values are set as the input variables. And then, YI values are denoted as the output variable. Table II shows the sample of input data from datasets used for the regression models.

E. The predictive performance analysis and computer configurations

As mentioned earlier, the outcomes of the predictive performances for LSSVR, PLSR, and PCR are \mathbb{R}^2 , RMSE, MAE, and t. RMSE is a conventional method used in a model evaluation [21], [52] that obtains the differences between the real and predicted values using 11. When RMSE values are lower, they indicate a better predictive performance of the model [6], [53], [54], [55]. Aside from that, \mathbb{R}^2 as shown in 12 is also used [56], [57]. The closer the \mathbb{R}^2 value is to 1, the better the fit.

$$RMSE = \sqrt{\frac{\sum_{i=1}^{N_T} (y_i - \hat{y}_i)^2}{N_T}} \quad (11)$$

where Y_i and \hat{Y}_i are the real and estimated output variables, respectively.

$$\mathbb{R}^2 = 1 - \frac{\sum (y_i - \hat{y}_i)^2}{\sum (\hat{y}_i - \bar{y})^2} \quad (12)$$

where \bar{y} is the mean value of y_i .

Moreover, in this study, MAE is also used to investigate the prediction of the regression models. MAE measures the mean magnitude of errors in a set of predictions regardless of the direction. The equation of MAE can be seen in 13 [58].

$$MAE = \sum \frac{|y_i - \hat{y}_i|}{N_T} \quad (13)$$

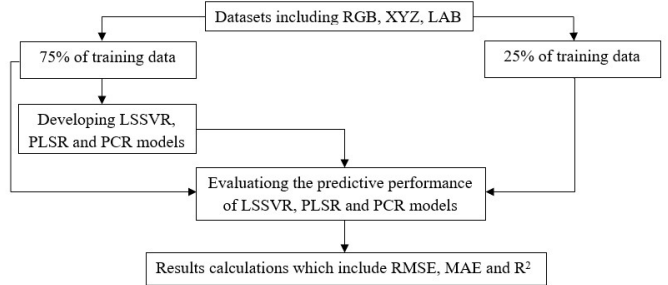


Figure 1. A flow diagram illustrating the data pipeline from the datasets to the obtained results.

Besides, computational times of all regressions for both training and a testing dataset which are denoted as t_1 and t_2 , respectively, are analyzed and compared. On the other hand, the LSSVR, PLSR, and PCR models were formulated and run on a laptop, namely Asus ZenBook UX305 and MATLAB version 2021. This laptop is equipped with 64-bit Windows 10; a 2.20 GHz Intel Core M3-6Y30 central processing unit processor, 4.0 GB of Random Access Memory, and 128 GB solid-state drive storage. Figure 1 displays a flow diagram illustrating the data pipeline from the datasets to the obtained results.

3. RESULTS AND DISCUSSIONS

As mentioned earlier, the LSSVR, PLSR, and PCR models are utilized to predict the YI values for the collected datasets. Then, the outcomes from these regression algorithms are depicted in Table III. From Table III, $RMSE_1$, \mathbb{R}^2 , and MAE_1 denote the RMSE, \mathbb{R}^2 , and MAE for training data. Meanwhile, $RMSE_2$, \mathbb{R}^2 , and MAE_2 are referring to the RMSE, \mathbb{R}^2 , and MAE for testing data. Furthermore, t_1 is the computational time for training data while t_2 is the computational load for testing data. From Table III, notice that LSSVR gives the lowest RMSE and MAE values, and it also has the highest \mathbb{R}^2 and t values. To be more specific, the $RMSE_1$ for LSSVR is 261,406% and 294,218% lower than PLSR and PCR while its $RMSE_2$ values are 725% and 772% smaller than PLSR and PCR. Also, its MAE_1 is lowered by 253,946% and 287,554% as compared to PLSR and PCR. Meanwhile, the MAE_2 for LSSVR is 1,365% which is 1,512% smaller than PLSR and PCR. Furthermore, LSSVR has 3% to 8% higher \mathbb{R}^2 for training and testing data than PLSR and PCR. This is due to the RBF kernel function in the LSSVR which can coordinate the data into higher dimensional space to have a superior predicted performance [11], [59], [60]. Meanwhile, LSSVR uses the LOO technique to tune the parameters to get optimal results. However, due to the presence of RBF kernel function and

TABLE II. A table showing the sample of input data from datasets

R	G	B	X	Y	Z	L	A	B	YI
255	254	238	2.51	2.53	2.40	99.35	-1.96	6.82	25.9
255	252	219	2.47	2.50	2.23	98.43	-3.97	15.29	25.9
255	251	200	2.43	2.48	2.07	97.80	-6.22	24.15	31.8
255	247	157	2.33	2.42	1.69	96.09	-9.50	43.48	45.4
255	245	134	2.28	2.39	1.48	95.28	-10.76	53.57	52.9

LOO technique, the computational times which are t_1 and t_2 for LSSVR are 100% higher than PLSR and PCR models.

From Table III, the PLSR has $RMSE_1$ and $RMSE_2$ which are 12.55% and 5.68% smaller than PCR while the MAE_1 and MAE_2 for PLSR are also 13.23% and 10.03% lower than PCR. Moreover, the R^2 values for PLSR are approximately 1% higher than PCR. The main reason for this result is due to the PLSR transformation objective being the optimum intersection between the output and input variables, however, PCR has optimized the block coverage within the input variables only [61]. Furthermore, PLSR also finds for the LVs that compute a simultaneous decomposition of input and output variables. These LVs explain the maximum covariance between the input and output variables [19]. Besides, both PLSR and PCR models have low computational burdens where their t_1 and t_2 are less than 1 sec. Additionally, Figures 2(i) and 2(ii) show the comparison of the real YI and the estimated YI values from LSSVR, PLSR, and PCR models for both datasets.

Notice that the predicted output which is the YI from the LSSVR is perfectly fixing the true data, hence it covers the true data which is a blue line in Figure 2(i). Moreover, it can be seen in Figures 2(i) and 2(ii) that all YI values are non-negative. In reality, the YI value for a yellow color sample must be non-negative and the non-positive YI values that do not represent yellow color are for a bluish object [62]. Hence, these non-negative YI values are displayed in Figures 3(i) and 3(ii) and also validated that the RGB values on the standard color chart are for yellow color objects and that the produced YI values are reasonable. Notice that these true and predicted YI values from all used regression models are closed while the R^2 values for all regression models shown in Table III are more than 0.9. The high values of R^2 for LSSVR, PLSR, and PCR indicate that these regression models fix the YI data well and can be employed to estimate the YI values [63]. Despite that, the LSSVR has the highest values of R^2 for both datasets as displayed in Table III as well as Figures 3(i) and 3(ii). Hence, in conclusion, the LSSVR has better predictive performance on YI values than the PLSR and PCR models.

4. CONCLUSIONS AND FUTURE WORK

In this study, a comparative study was performed to examine the LSSVR, PLSR, and PCR models' performance in the estimation of the YI values. Moreover, the dataset was collected using a standard RGB-listed color chart.

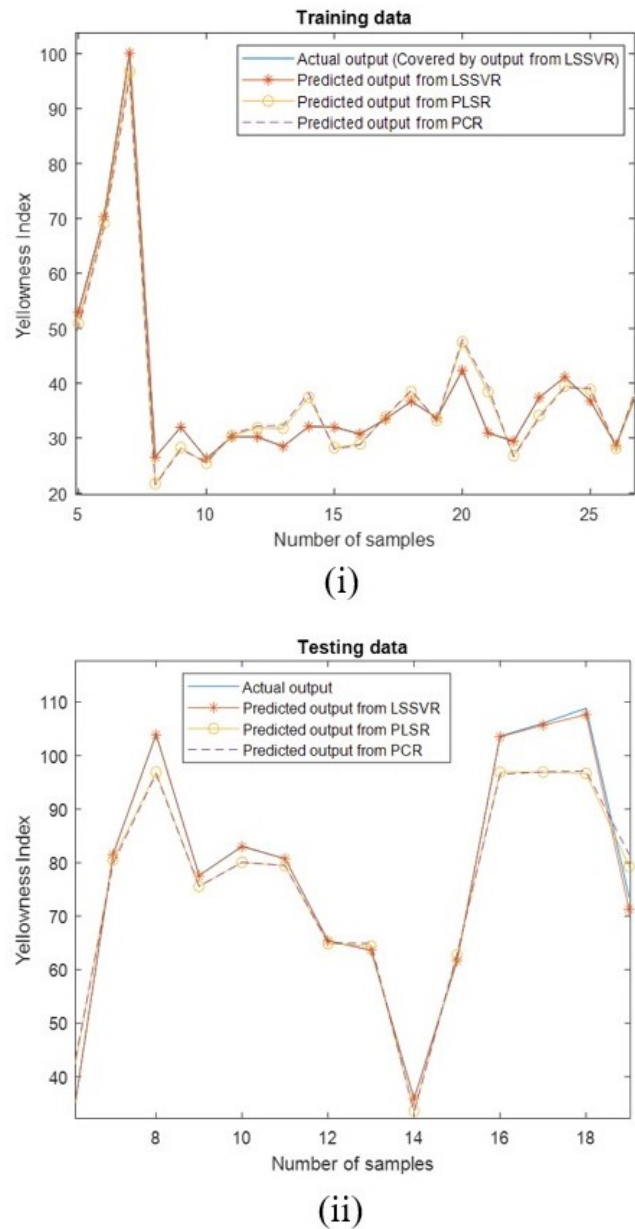


Figure 2. The comparison of the true values and the estimated YI values from LSSVR, PLSR, and PCR models for, (i) Training data, and (ii) Testing data.



TABLE III. The obtained outcomes were from PLSR, LSSVR, and PCR methods

Results	LSSVR	PLSR	PCR
$RMS E_1$	0.0015	3.8159	4.2947
MAE_1	0.0012	2.9381	3.3268
R_1^2	1.0000	0.9680	0.9592
t_1 (sec)	10.9428	0.0052	0.0039
$RMS E_2$	0.5962	4.9203	5.2000
MAE_2	0.2360	3.4573	3.8040
R_2^2	0.9992	0.9269	0.9181
t_2 (sec)	10.8914	0.0032	0.0032

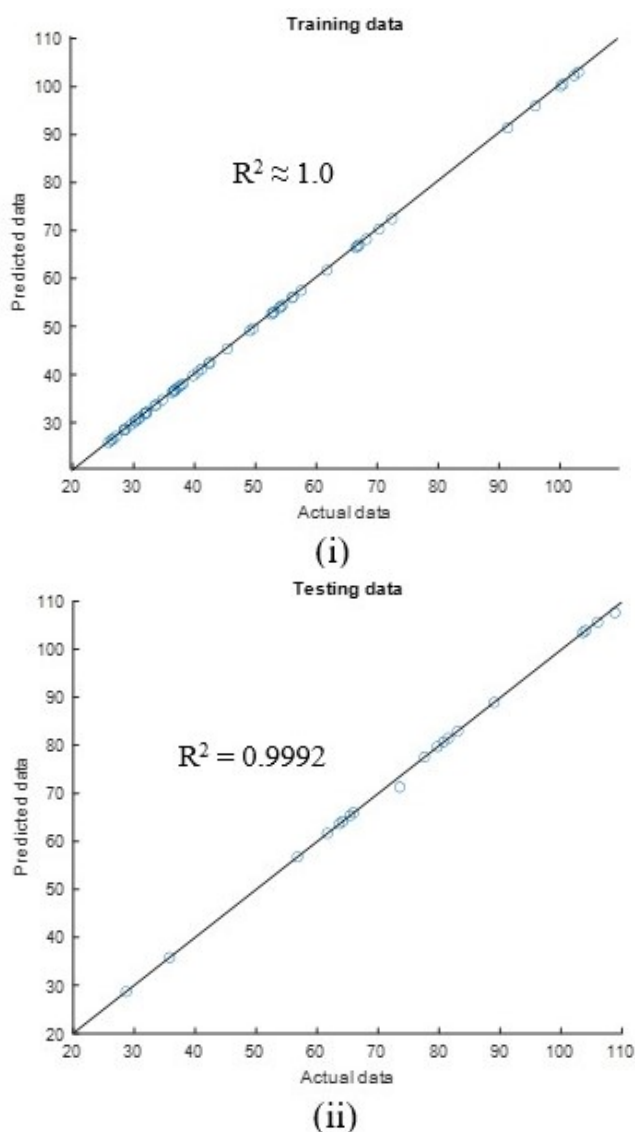


Figure 3. Correlation between the true and estimated YI values for, (i) Training data, and (ii) Testing data.

This collected dataset was used as both datasets for the PLSR, LSSVR, and PCR models development and evaluation. Then, the predictive outcomes from PLSR, LSSVR, and PCR methods on YI estimation were evaluated and compared. From the results, notice that LSSVR performed much superior to PLSR and PCR on the forecasting of YI values. The outcomes show that the RMSE values of both datasets for LSSVR are roughly 725% to 294,218% smaller than PLSR and PCR. Moreover, the MAE values of both datasets for LSSVR are 1,365% to 287,554% smaller than PLSR and PCR. The computational times for LSSVR, PLSR, and PCR models are relatively low, which are less than 11 sec.

Nevertheless, the computational times for both datasets for LSSVR are 100% much higher than both PLSR and PCR. Despite that, the R^2 values of both datasets for LSSVR are higher and closer to 1 as compared to PLSR and PCR. Moreover, R^2 values for PLSR, LSSVR, and PCR are greater than 0.9 which denotes lesser dissimilarities between the true and predicted YI values from these regression models. Hence, these regression models can be utilized to estimate the YI on a yellowish sample and be an alternative to the pricy color measurement instruments such as spectrophotometers and colorimeters.

YI is computed from color scale parameters that assess perceptual yellowness [64]. However, the color data to calculate YI values is usually measured by expensive hardware instruments. Furthermore, a direct and rapid YI estimation utilizing this hardware equipment is impossible. The purchasing cost of a spectrophotometer is roughly \$5,000 while a colorimeter costs between \$5,500 to \$6,500 [65], [66]. From the results, LSSVR performed much better than PLSR and PCR, and hence it is more suitable to be integrated with the MATLAB mobile apps. Hence, this research study can introduce a novel tool to measure the YI value of an object. On the other hand, the future study can investigate the performance of the LSSVR model in real-time in YI values measurement using the existing MATLAB mobile app where the different light intensity levels, denoising of the taken images, image enhancement, and image restoration can be further investigated.



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AUTHOR CONTRIBUTIONS STATEMENT

Wan Sieng Yeo collected samples, validated methodology, conducted simulations, did data analysis, and wrote, reviewed, and edited the paper. Agus Saptoro helped to edit and improve the paper.

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